

INSTRUCTIONS

for the Ohio Department of Transportation GUIDE FOR DETERMINING TIME REQUIREMENTS FOR TRAFFIC SIGNAL PREEMPTION AT HIGHWAY-RAIL GRADE CROSSINGS Version DRAFT 11-10-2009

BACKGROUND

The Ohio Department of Transportation (ODOT) *Guide for Determining Time Requirements for Traffic Signal Preemption at Highway-Rail Grade Crossings*, also known as the ODOT Preemption Worksheet, and these instructions are an adaptation of the Texas Department of Transportation (TxDOT) *Guide for Determining Time Requirements for Traffic Signal Preemption at Highway-Rail Grade Crossings* and associated instructions originally developed for TxDOT by the Texas Transportation Institute.

USING THESE INSTRUCTIONS

The purpose of these instructions is to assist ODOT and Local Highway Authority personnel in completing the Preemption Worksheet. The main purpose of the Preemption Worksheet is to determine if additional time (advance preemption) is required for the traffic signal to move stationary vehicles out of the crossing before the arrival of the train.

SITE DESCRIPTIVE INFORMATION:

Enter the location for the highway-rail grade crossing including the (nearest) **City**, the **County** in which the crossing is located, and the ODOT **District** number.

Next, enter the **Date** the analysis was performed, your (the analyst's) name next to "**Completed by**," and the status of the **District Approval** for this crossing.

To complete the reference schematic for this site, place a **North Arrow** in the provided circle to correctly orient the crossing and roadway. Record the name of the **Parallel Street** and the **Crossing Street** in the spaces provided, and remember to include any "street sign"/local name for the streets as well as any state/US/Interstate designation (i.e., "CR-7," "SR 12," "US 30," "IH 70 [frontage]"). You may wish to note other details on the intersection/crossing diagram as well, including the number of lanes and/or turn bays on the intersection approach crossing the tracks and any adjacent land use.

Enter the **Railroad** name, **Railroad Contact** person's name, and **Phone** number for the responsible railroad company and its equipment maintenance and operations contractor (if any). Finally, record the unique 7-character **Crossing DOT#** (6 numeric plus one alphanumeric characters) for the crossing.

Note that this guide for determining time requirements for traffic signal preemption requires you to input many traffic signal controller unit timing/phasing values. To preserve the accuracy of these values, record all values to the next highest tenth of a second (i.e., record 5.42 seconds as 5.5 seconds).

SECTION 1: RIGHT-OF-WAY TRANSFER TIME CALCULATION

Preempt Verification and Response Time

Line 1. Programmed preempt delay time is the amount of time, in seconds, that the traffic signal controller unit is programmed to wait from the initial receipt of a preempt call until the call is "verified" and considered a viable request for transfer into preemption mode. Preempt delay time is a value entered into the controller unit for purposes of preempt call validation, and may not be available on all manufacturer's controllers.

Line 2. Controller response time to preempt is the time, in seconds, that elapses while the traffic signal controller unit electronically registers the preempt call (i.e., it is the controller's equipment response time for the preempt call). The controller unit manufacturer should be consulted to find the correct value for use here. For future reference, you may wish to record the controller type in the "Remarks" section to the right of the controller response time to preempt value. However, note that the manufacturer's given response time may be unique for a controller's model and software generation; other models and/or software generations may have different response times.

Line 3. Preempt verification and response time is the sum of Line 1 and Line 2. It represents the number of seconds between the receipt at the traffic signal controller unit of a preempt call issued by the railroad's grade crossing warning equipment and the time the controller software actually begins to respond to the preempt call (i.e., by transitioning into preemption mode).

Worst-Case Conflicting Vehicle Time

Line 4. Worst-case conflicting vehicle phase number is the number of the controller unit phase which conflicts with the phase(s) used to clear the tracks—the track clearance phase(s)—that has the longest sum of minimum green (if provided), other (additional) green time (if provided), yellow change interval, and red clearance interval durations that may need to be serviced during the transition into preemption. Note that all of these time elements are for vehicular phases only; pedestrian phase times will be assessed in the next part of the analysis. The worst-case vehicle phase can be any phase that must be terminated prior to serving the track clearance phase(s) and may even include the track clearance phase if it is terminated to avoid a yellow trap condition for a permissive left turn opposite of the track clearance phase.

Line 5. Minimum green time during right-of-way transfer is the number of seconds that the worst-case vehicle phase (see Line 4 discussion) must display a green indication before the controller unit will terminate the phase through its yellow change and red clearance intervals and transition to the track clearance green interval. The minimum green time during right-of-way transfer may be set to zero to allow as rapid a transition as possible to the track clearance green interval. However, local policies will govern the amount of minimum green time provided during the transition into preemption. Standard ODOT practice is to provide for at least 4 seconds of minimum green time before transitioning into preemption if the controller unit is capable of such a setting to avoid unexpected short green intervals.

Line 6. Other green time during right-of-way transfer is any additional green time that is preserved beyond the preempt minimum green time for the worst-case vehicle phase (Line 4). Given the time-critical nature of the transition to the track clearance green interval during preempted operation, this value is usually zero except in unusual circumstances. One situation where other green time may be present is when a trailing green overlap is used on the worst-case vehicle phase, and the controller unit is set up to time out the trailing green overlap on entry into preemption.

Line 7. Yellow change time is the required yellow change interval time for the worst-case vehicle phase (Line 4) given prevailing operating conditions. Yellow change time for the phase under preemption is usually the same value, in seconds, programmed for the phase under normal operating circumstances. Section 4D.13 of the *Ohio Manual on Uniform Traffic Control Devices* (*OMUTCD*) states that the normal yellow change interval shall not be shortened or omitted during the transition into preemption control.

Line 8. Red clearance time is the required red clearance interval for the worst-case vehicle phase (Line 4) given prevailing operating conditions. Red clearance time for the phase under preemption is usually the same value, in seconds, programmed for the phase under normal operating circumstances. Section 4D.13 of the *OMUTCD* states that the normal red clearance interval shall not be shortened or omitted during the transition into preemption control.

Line 9. Worst-case conflicting vehicle time is the sum of Lines 5 through 8. This value will be compared with the worst-case conflicting pedestrian time to determine whether vehicle or pedestrian phase times are the most critical in their impact on warning time requirements during the transition to the track clearance green interval.

Worst-case Conflicting Pedestrian Time

Line 10. Worst-case pedestrian phase number is the pedestrian phase number (referenced as the vehicle phase number that the pedestrian phase is associated with) that has the longest sum of walk time, pedestrian change (i.e., flashing don't walk) time, and associated vehicle clearance times that have to be provided during the transition into preemption. The worst-case pedestrian phase is not restricted to pedestrian phases running concurrently with vehicle phases that serve traffic parallel to the tracks. The vehicle phase associated with the worst-case pedestrian phase may even be one of the track clearance phases if the pedestrian phase is not serviced concurrently with the associated track clearance phase.

Line 11. Minimum walk time during right-of-way transfer is the minimum pedestrian walk time for the worst-case pedestrian phase (Line 10). The *OMUTCD* permits the shortening (i.e. truncation) or complete omission of the pedestrian walk interval. A zero value allows for the most rapid transition to the track clearance green interval. However, the minimum pedestrian walk time is typically set based on local policies, which may or may not allow truncation and/or omission. Standard ODOT practice is to set this number to zero and to set timing values or preemption settings accordingly in the controller unit.

Line 12. Pedestrian change time during right-of-way transfer is the flashing don't walk time for the worst-case pedestrian phase. The *OMUTCD* permits the shortening (i.e. truncation) or complete omission of the pedestrian change interval. A zero value allows for the most rapid transition to the track clearance green interval. However, the pedestrian change time is typically set based on local policies, which may or may not allow truncation and/or omission. Standard ODOT practice is to set this number to the required pedestrian clearance time as per *OMUTCD* Section 4E.10 less the associated yellow change and red clearance time.

Line 13. Yellow change time is the required yellow change interval time for the worst-case pedestrian phase (Line 10) given prevailing operating conditions. Yellow change time for the phase under preemption is usually the same value, in seconds, programmed for the phase under normal operating circumstances. Section 4D.13 of the *Ohio Manual on Uniform Traffic Control Devices* (*OMUTCD*) states that the normal yellow change interval shall not be shortened or omitted during the transition into preemption control.

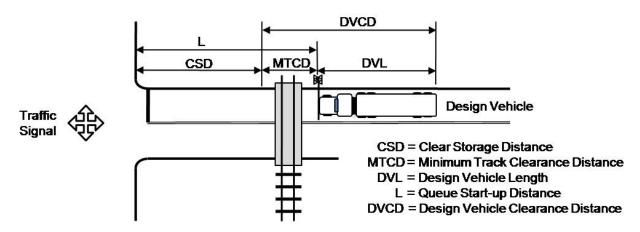
Line 14. Red clearance time is the required red clearance interval for the worst-case pedestrian phase (Line 10) given prevailing operating conditions. Red clearance time for the phase under preemption is usually the same value, in seconds, programmed for the phase under normal operating circumstances. Section 4D.13 of the *OMUTCD* states that the normal red clearance interval shall not be shortened or omitted during the transition into preemption control.

Line 15. Worst-case conflicting pedestrian time is the sum of Lines 11 through 14. This value will be compared to the worst-case conflicting vehicle time to determine whether vehicle or pedestrian phase times are the most critical in their impact on warning time requirements during the transition to the track clearance green interval.

Worst-case Conflicting Vehicle or Pedestrian Time

Line 16. Worst-case conflicting vehicle or pedestrian time is the maximum value of the worst-case conflicting vehicle time (Line 9) or the worst-case conflicting pedestrian time (Line 15).

Line 17. Right-of-way transfer time is the maximum amount of time needed by the traffic signal controller unit, for the worst-case condition, from the initial receipt of the preempt call to the display of the track clearance green interval. Right-of-way transfer time is the sum of the preemption verification and response time (Line 3) and the worst-case conflicting vehicle or pedestrian time (Line 16).



SECTION 2: QUEUE CLEARANCE TIME CALCULATION

Figure 1 Queue Clearance Distances

Line 18. Clear storage distance (CSD), as shown in Figure 1, is the shortest distance, in feet, along the crossing street between the edge of the grade crossing nearest the signalized intersection—identified by a Line parallel to the rail 6 feet (2 m) from the rail nearest to the intersection—and the edge of the street or shoulder of street that parallels the tracks. If the normal stopping point on the crossing street is significant different from the edge or shoulder of parallel street, measure the distance to the normal stopping point. For angled (i.e., non-perpendicular) railroad crossings, always measure the distance along the inside (centerline) edge of the leftmost lane or the distance along the outside (shoulder) edge of the rightmost lane, as appropriate, to determine the shortest clear storage distance and record that value.

Line 19. Minimum track clearance distance (MTCD), as shown in Figure 1, is the length, in feet, along the highway at one or more railroad tracks, measured from the railroad crossing stop line, warning device, or 12 feet (4 m) perpendicular to the track centerline—whichever is further away from the tracks, to 6 feet (2 m) beyond the tracks measured perpendicular to the far rail. For angled (i.e., non-perpendicular) railroad crossings, always measure the distance along the inside (centerline) edge of the leftmost lane or the distance along the outside (shoulder) edge of the rightmost lane, as appropriate, to determine the longest minimum track clearance distance and record that value.

Line 20. Design vehicle length (DVL), as shown in Figure 1, is the length, in feet, of the design vehicle, the longest vehicle permitted by road authority statute on the subject roadway. In the "Remarks" section to the right of the data entry box for Line 20, note the design vehicle type for ease of reference. Some design vehicles from the *AASHTO Green Book (A Policy on Geometric Design of Highways and Streets)* are given in Table 1. Note that the Ohio Revised Code Section 5577.05(C)(6) prescribes the maximum length of combination vehicles as 65 feet.

Table 1.	AASHTO Design	Vehicle Len	gths	
			-	-

Design Vehicle Type	Symbol	Length (ft)		
Passenger Car	Р	19		
Single Unit Truck	SU	30		
Large School Bus	S-BUS 40	40		
Intermediate Semi-Trailer	WB-50	55		
Large Semi-Trailer	WB-60	65		

Line 21. Average grade over crossing is the average grade, in percent, of the roadway in the direction of travel approaching the intersection over the area of the roadway beginning at a point equal to the design vehicle length in advance of the railroad warning device(s) and ending at a point the design vehicle length beyond the MTCD.

Line 22. Queue start-up distance (L), as shown in Figure 1, is the maximum length, in feet, over which a queue of vehicles stopped for a red signal indication at an intersection downstream of the crossing must get in motion so that the design vehicle can move out of the railroad crossing prior to the train's arrival. Queue start-up distance is the sum of the clear storage distance (Line 18) and minimum track clearance distance (Line 19).

Line 23. Time required for the design vehicle to start moving is the time elapsed between the start of the track clearance green interval and the time the design vehicle, which is located at the edge of the railroad crossing on the opposite side from the signalized intersection, begins to move. This elapsed time is based on a "shock wave" speed of 20 feet per second and a 2 second start-up time (the additional time for the first driver to recognize the signal is green and move his/her foot from the brake to the accelerator). The time required for the design vehicle to start moving is calculated, in seconds, as 2 plus the queue start-up distance, L (Line 22) divided by the wave speed of 20 feet per second. The time required for the design vehicle as well as a limited level of driver inattentiveness. This value may be overridden by local observation, but care must be taken to identify the worst-case (longest) time required for the design vehicle to start moving.

Line 24. Design vehicle clearance distance (DVCD), as shown in Figure 1, is the length, in feet, which the design vehicle must travel in order to enter and completely pass through the railroad crossing's minimum track clearance distance (MTCD). It is the sum of the minimum track clearance distance (Line 19) and the design vehicle's length (Line 20).

Line 25. Time for design vehicle to accelerate through the DVCD is the amount of time required for the design vehicle to accelerate from a stop and travel the complete design vehicle clearance distance. This time value can be found through local observation or by using Figure 2. If local observation is used, take care to identify the worst-case (longest) time required for the design vehicle to accelerate through the DVCD. If Figure 2 is used to estimate the time for the design vehicle to accelerate through the DVCD, locate the DVCD from Line 24 on the horizontal axis of Figure 2 and then draw a line straight up until that line intersects the acceleration time performance curve for your design vehicle. Then, draw a horizontal line from this point to the left until it intersects the vertical axis, and record the appropriate acceleration time. Round up to the next higher tenth of a second. For example, with a DVCD of 80 feet and a WB-50 semi-trailer design vehicle on a level surface, the time required for the design vehicle to accelerate through the DVCD will be 12.2 seconds.

If your design vehicle is a semi-trailer, large school bus, or single unit vehicle, you may need to apply a correction factor to estimate the effect of grade on the acceleration of the vehicle. If the average grade over the crossing from Line 21 is 1% uphill (+1%) or greater, multiply the acceleration time obtained from Figure 2 with the factor obtained from Table 2 and round up to the next higher tenth of a second to get an estimate of the acceleration time on the grade. For example, with a DVCD of 80 feet and a WB-50 semi-trailer design vehicle on a 4% uphill, the (interpolated) factor from Table 2 is 1.30. Therefore, the

estimated time required for the design vehicle to accelerate through the DVCD will be $12.2 \times 1.30 = 15.86$ seconds, or 15.9 seconds rounded up to the next higher tenth of a second.

If you selected a design vehicle different from those listed in Figure 2 and Table 2, you may still be able to use Figure 2 and Table 2 if you can match your design vehicle to the weight, weight-to-power ratio, and power application characteristics of the design vehicles in Figure 2 and Table 2. The WB-50 curve and grade factors are based on an 80,000 lb vehicle with a weight-to-power ratio of 400 lb/hp accelerating at 85% of its maximum power on level grades and at 100% of its maximum power on uphill grades, and may therefore be representative of any heavy tractor-trailer combination with the same characteristics. **The WB-50 curve should be used for WB-50 and WB-60 semi-trailer design vehicles.** The school bus curve and grade factors are based on a 27,000 lb vehicle with a weight-to-power ratio of 180 lb/hp accelerating at 70% of its maximum power on level grades and at 85% of its maximum power on uphill grades. The SU curve and grade factors are based on a 34,000 lb vehicle with a weight-to-power ratio of 180 lb/hp accelerating at 75% of its maximum power on level grades and at 85% of its maximum power on uphill grades.

For design vehicle clearance distances greater than 400 feet, use Equation 1 to estimate the time for the design vehicle to accelerate through the design vehicle clearance distance or any other distance:

$$T = e^{\left[a - b\sqrt{c + \frac{2}{b}\ln\left(\frac{d}{X}\right)}\right]}$$

Equation 1

where

T = time to accelerate through distance X, in seconds;

X = distance over which acceleration takes place, in feet;

In = natural logarithm function;

e = 2.17828, the base of natural logarithms; and

a, b, c, and d = calibration parameters from Table 3.

Note: To interpolate between grades, do not interpolate the parameters in Table 3. The correct way to interpolate is to calculate the acceleration time T using Equation 1 for the two nearest grades and then interpolate between the two acceleration times.

Line 26. Queue clearance time (QCLR) is the total amount of time required (after the signal has turned green for the approach crossing the tracks) to begin moving a queue of vehicles through the queue startup distance (L, Line 22) and then move the design vehicle from a stopped position at the far side of the crossing completely through the minimum track clearance distance (MTCD, Line 19). This value is the sum of the time required for design vehicle to start moving (Line 23) and the time for design vehicle to accelerate through the design vehicle clearance distance (Line 25).

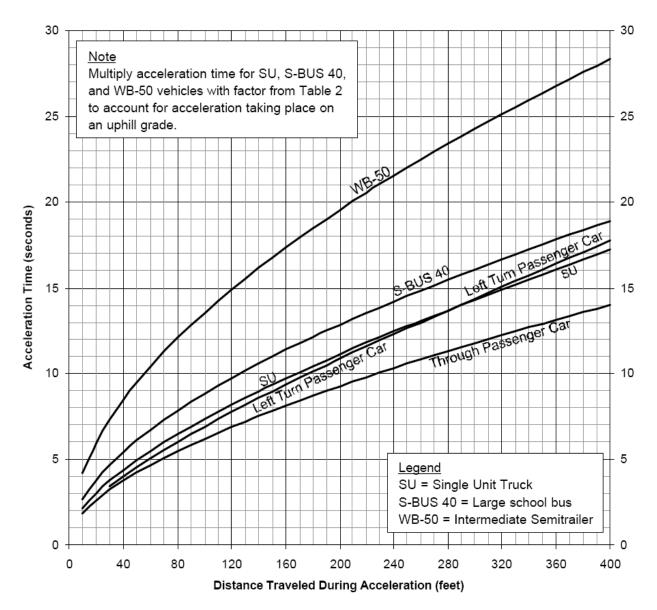


Figure 2 Acceleration time over a fixed distance on a level surface.

Acceleration	Design Vehicle and Percentage Uphill Grade													
Distance	Single Unit Truck				Large School Bus				Intermediate Tractor-Trailer					
	(SU)			(S-BUS 40)				(WB-50)						
(ft)	0-2%	4%	6%	8%	0-1%	2%	4%	6%	8%	0%	2%	4%	6%	8%
25	1.00	1.06	1.13	1.19	1.00	1.01	1.10	1.19	1.28	1.00	1.09	1.27	1.42	1.55
50	1.00	1.09	1.17	1.25	1.00	1.01	1.12	1.21	1.30	1.00	1.10	1.28	1.44	1.58
75	1.00	1.10	1.19	1.29	1.00	1.02	1.13	1.23	1.33	1.00	1.11	1.30	1.47	1.61
100	1.00	1.11	1.21	1.32	1.00	1.02	1.14	1.25	1.35	1.00	1.11	1.31	1.48	1.64
125	1.00	1.12	1.23	1.34	1.00	1.03	1.15	1.26	1.37	1.00	1.12	1.32	1.50	1.66
150	1.00	1.12	1.24	1.37	1.00	1.03	1.16	1.28	1.40	1.00	1.12	1.33	1.52	1.68
175	1.00	1.13	1.25	1.38	1.00	1.03	1.17	1.29	1.42	1.00	1.12	1.34	1.53	1.70
200	1.00	1.13	1.26	1.40	1.00	1.04	1.17	1.30	1.43	1.00	1.13	1.35	1.54	1.72
225	1.00	1.14	1.27	1.42	1.00	1.04	1.18	1.32	1.45	1.00	1.13	1.35	1.56	1.74
250	1.00	1.14	1.28	1.43	1.00	1.04	1.19	1.33	1.47	1.00	1.13	1.36	1.57	1.76
275	1.00	1.14	1.29	1.44	1.00	1.05	1.20	1.34	1.49	1.00	1.14	1.37	1.58	1.77
300	1.00	1.14	1.30	1.46	1.00	1.05	1.20	1.35	1.50	1.00	1.14	1.37	1.59	1.79
325	1.00	1.15	1.30	1.47	1.00	1.05	1.21	1.36	1.52	1.00	1.14	1.38	1.60	1.81
350	1.00	1.15	1.31	1.48	1.00	1.05	1.22	1.37	1.54	1.00	1.15	1.39	1.61	1.82
375	1.00	1.15	1.31	1.49	1.00	1.06	1.22	1.38	1.55	1.00	1.15	1.39	1.62	1.84
400	1.00	1.15	1.32	1.50	1.00	1.06	1.23	1.40	1.57	1.00	1.15	1.40	1.63	1.85

Table 2. Factors to account for slower acceleration on uphill grades. Multiply the appropriate factor (depending on the design vehicle, grade, and acceleration distance) with the acceleration time in Figure 2 to obtain the estimated acceleration time on the grade.

Table 3. Parameters to estimate vehicle acceleration times over distances greater than 400 feet using Equation 1.

Design Vehicle	Grade	а	b	С	d
Through Passenger Car	Level	7.75	3.252	5.679	2.153
Left Turning Passenger Car	Level	10.29	5.832	3.114	5.090
	Level to 2%	8.16	3.624	5.070	2.018
Single Unit Truck	4%	10.39	4.865	4.560	1.739
(SU)	6%	9.52	4.542	4.393	1.700
	8%	9.38	4.597	4.165	1.668
	Level to 1%	10.02	4.108	5.95	0.885
Large School Bus	2%	11.51	5.254	4.801	1.300
(S-BUS 40)	4%	10.79	5.042	4.577	1.266
(8-808 40)	6%	10.61	5.101	4.329	1.253
	8%	11.84	6.198	3.652	1.554
	Level	17.75	7.984	4.940	0.481
Intermediate Semi-Trailer	2%	10.26	4.026	6.500	0.249
	4%	9.39	3.635	6.670	0.193
(WB-50)	6%	9.38	3.732	6.310	0.188
	8%	10.31	4.515	5.219	0.265

SECTION 3: MAXIMUM PREEMPTION TIME CALCULATION

Line 27. Right-of-way transfer time (RWTT), from Line 17, is the maximum amount of time needed for the worst case condition, prior to display of the track clearance green interval.

Line 28. Queue clearance time (QCLR), from Line 26, starts simultaneously with the track clearance green interval (i.e. after right-of-way transfer), and is the time required for the design vehicle stopped just inside the minimum track clearance distance to start up and move completely out of the minimum track clearance distance.

Line 29. Desired minimum separation time (ST), is a time "buffer" between the departure of the last vehicle (the design vehicle) from the railroad crossing (as defined by the minimum track clearance distance) and the arrival of the train. Separation time is added for safety reasons and to avoid driver discomfort. If no separation time is provided, a vehicle could potentially leave the crossing at exactly the same time the train arrives, which would certainly lead to severe driver discomfort and potential unsafe behavior. The recommended value of four (4) seconds is a based on the minimum recommended value found in the Institute of Transportation Engineer's *ITE Journal* (in an article by Marshall and Berg in February 1997). Larger values may be appropriate for long clear storage distances, high speed trains, and high percentage of trucks.

Line 30. Maximum preemption time (MPT) is the total amount of time required after the preempt is initiated by the railroad warning equipment to complete right-of-way transfer to the track clearance green interval, initiate the track clearance phase(s), move the design vehicle out of the crossing's minimum track clearance distance, and provide a separation time "buffer" before the train arrives at the crossing. It is the sum of the right-of-way transfer time (Line 27), the queue clearance time (Line 28), and the desired minimum separation time (Line 29).

MPT = RWTT + QCLR + ST

SECTION 4: SUFFICIENT WARNING TIME CHECK

Line 31. Minimum time (MT) is the least amount of time active warning devices shall operate prior to the arrival of a train at a highway-rail grade crossing. Section 8D.06 of the *OMUTCD* requires that flashing-light signals shall operate for at least 20 seconds before the arrival of any train, except on tracks where all trains operate at less than 30 km/h (20 mph) and where flagging is performed by an employee on the ground.

Line 32. Wide crossing clearance time (CT) is additional time that may be provided by the railroad to account for longer crossing time at wide (i.e., multi-track crossings) or skewed-angle crossings. You must obtain the clearance time from the railroad responsible for the railroad crossing. In cases where the minimum track clearance distance (Line 19) exceeds 35 feet, the railroads' *AREMA Manual* requires clearance time of one second be provided for each additional 10 feet, or portions thereof, over 35 feet.

Line 33. Additional CT is additional time that may be specified by the railroad or the public agency to account for site-specific needs. Examples of additional clearance time include time provided for simultaneous preemption (where the preemption notification is sent to the signal controller unit simultaneously with the activation of the railroad crossing's active warning devices), additional gate delay time, and adjacent track clearance time.

Line 34. Minimum warning time (MWT) provided by the railroad is the sum of the minimum time (Line 31), the wide crossing clearance time (Line 32), and additional CT (Line 33). This value is the actual minimum time that active warning devices can be expected to operate at the crossing prior to the arrival of the train under normal, through-train conditions. The term "through-train" refers to the case where trains do not stop or start moving while near or at the crossing. Note that the minimum warning time does

not include buffer time (BT). Buffer time is added by the railroad to ensure that the minimum warning time is always provided despite inherent variations in warning times; however, it is not consistently provided and cannot be relied upon by the traffic engineer for signal preemption and/or warning time calculations.

MWT = MT + CT

Line 35. Minimum amount of advance preemption time (APT) needed from railroad is the additional time needed (if any), that is required to provide safe preemption in the worst case (the maximum preemption time on Line 30), given the minimum warning time provided by the railroad (Line 34). The APT needed is calculated by subtracting the minimum warning time provided by the railroad (Line 34) from the maximum preemption time (Line 30). If the result of the subtraction is equal to or less than zero, it means that sufficient minimum warning time is available, and you should enter zero (0) on Line 35.

APT = MPT - MWT

If the APT on Line 35 is greater than zero (0), it means that the minimum warning time provided by the railroad is insufficient, and additional warning time in the form of advance preemption time has to be requested from the railroad to ensure safe operation.

As an alternative, it may be possible to reduce the maximum preemption time (Line 30). To reduce the maximum preemption time, you can reduce either the programmable preempt delay time (Line 1), if this is possible; reduce preempt minimum green time (Line 5) or other green time (Line 6), as long as you do not violate local policies for signal timing; or, reduce yellow change time (Line 7) or red clearance time (Line 8) as long as adequate and appropriate yellow change and red clearance intervals are provided as per the *OMUTCD* Section 4D.10 and applicable guidelines such as the Institute of Transportation Engineers' *Determining Vehicle Signal Change and Clearance Intervals*.

If pedestrian rather than vehicular phasing controls warning time requirements for preemption, it may be possible to reduce the minimum walk time (Line 11) and/or pedestrian change time (Line 12) as long as you do not violate local policies for signal timing.

Once you have made all of the possible adjustments to the warning time, recompute the totals in Lines 3, 9, 15, 16, 17, 27, 30, and 35. If Line 35 remains greater than zero, then you will have to request advance preemption time from the railroad, as described above, to ensure safe preemption of the adjacent signalized intersection.

SECTION 5: VEHICLE-GATE INTERACTION CHECK

Note: This section is used to calculate the required advance preemption time to avoid the automatic gates descending on a stationary or slow moving design vehicle as it moves through the minimum track clearance distance (MTCD). If this worksheet is only used to determine if additional warning time has to be requested from the railroad to ensure that vehicles have enough time to clear the crossing before the arrival of the train, this section need not be completed.

Line 36. Right-of-way transfer time, from Line 17, is the maximum amount of time needed for the worst case condition, prior to display of the track clearance green interval.

Line 37. Time required for design vehicle to start moving, from Line 23, is the time elapsed between the start of the track clearance green interval and the time the design vehicle, which is located at the edge of the railroad crossing on the opposite side from the signalized intersection, begins to move.

Line 38. Time required for design vehicle to accelerate through the DVL is the time required for the design vehicle to accelerate through its own length. The design vehicle length is recorded on Line 20.

This time value, in seconds, can be read from Figure 2 and Table 2 or looked up in Table 4 for standard design vehicles.

Design Vehicle	Design Vehicle Length (feet)	Grade	Acceleration Time (seconds)	
Through Passenger Car	19	Level	2.6	
Left Turning Passenger Car	19	Level	2.7	
		Level to 2%	3.8	
Single Unit Truck	30	4%	4.0	
(SU)	30	6%	4.3	
		8%	4.6	
		Level to 1%	5.5	
Large School Bus		2%	5.5	
(S-BUS 40)	40	4%	6.1	
		6%	6.6	
		8%	7.0	
		Level	10.0	
Intermediate Semi-Trailer	55	2%	11.0	
(WB-50)		4%	12.8	
(110-50)		6%	14.4	
		8%	15.8	

 Table 4. Time required for the design vehicle to accelerate through the design vehicle length.

Line 39. Time required for design vehicle to clear the descending gates is the sum of the right-ofway transfer time (Line 36), the time required for design vehicle to start moving (Line 37), and the time required for design vehicle to accelerate through the design vehicle length (Line 38).

Line 40. Duration of flashing lights before gate descent start is the time the railroad warning lights flash before the gates start to descend. This value typically ranges from 3 to 5 seconds and must be obtained from the railroad. The value obtained from the railroad may be verified using field observation.

Line 41. Full gate descent time is the time it takes for the gates to descend to a horizontal position after they start their descent. This value must be obtained from the railroad and may be verified using field observation. In the case where multiple gates descend at different speeds, use the descent time of the gate that reaches the horizontal position first.

Line 42. Distance from center of gate support to design vehicle (d), as shown in Figure 3, is the distance, in feet, from the center of the gate mechanism to the nearest side of the design vehicle.

Line 43. Proportion of non-interaction gate descent time is the decimal proportion of the full gate descent time on Line 41 during which the gate will not interact with (i.e. not hit) the design vehicle if it is located under the gate. This value depends on the design vehicle height, h, and the distance from the center of the gate mechanism to the nearest side of the design vehicle, d, as recorded on Line 42. Figure 4 can be used to determine the proportion of non-interaction gate descent time. Select the distance from the center of the gate mechanism to the nearest side of the design vehicle, d, on the vertical axis of Figure 4, draw a horizontal line until you reach the curve that represents the design vehicle, and then

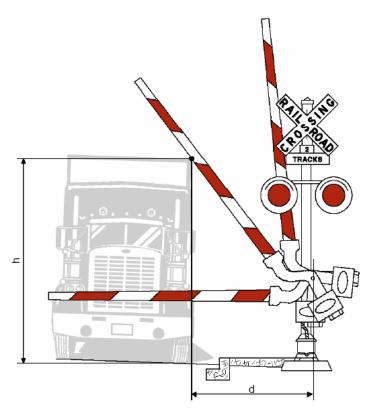


Figure 4 Gate interaction with the design vehicle.

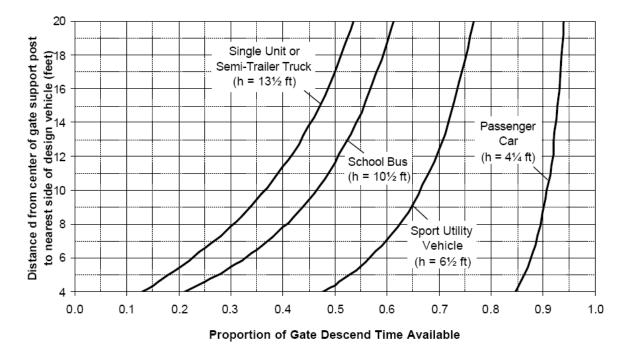


Figure 5 Proportion of gate descent time available as a function of the design vehicle height and the distance from the center of the gate mechanism to the nearest side of the design vehicle.

draw a vertical line down to the horizontal axis and read off the value of the proportion of non-interaction gate descent time.

Line 44. Non-interaction gate descent time is time during gate descent that the gate will not interact with (i.e. not hit) the design vehicle if it is located under the gate. In other words, it is the time that expires after the gate starts to descend until it hits the design vehicle if it is located under the gate. This value is calculated by multiplying the full gate descent time (Line 41) with the proportion of non-interaction gate descent time (Line 43).

Line 45. Time available for design vehicle to clear descending gate is the time after the railroad warning lights start to flash that is available for the design vehicle to clear the descending gate before the gate hits the vehicle. It is the sum of the duration of the flashing lights before gate descent start (Line 40) and the non-interaction gate descent time (Line 44).

Line 46. Advance preemption time (APT) required to avoid design vehicle-gate interaction is calculated by subtracting the time available for the design vehicle to clear descending gate (Line 45) from the time required for the design vehicle to clear descending gate (Line 39). The result is the amount of advance preemption time that is required to avoid the gates descending on a stationary or slow-moving design vehicle.

It should be kept in mind that on its own, gates descending on a vehicle is not a critical safety failure, because enough time still exists to clear the crossing before the arrival of the train, if the advance preemption time on Line 35 is provided. Therefore, local policies may vary on whether additional advance preemption time (over and above that on Line 35) should be requested solely for the purpose of prohibiting gates descending on vehicles.

SECTION 6: TRACK CLEARANCE GREEN TIME CALCULATION

Note: This section is used to calculate the duration of the track clearance green interval.

The objective of the section is to calculate the duration of the track clearance green interval to ensure safe and efficient operations at the crossing and adjacent traffic signal.

The Preempt Trap Check section (Lines 47 to 55) focuses on safety by calculating the minimum duration of the track clearance green interval to ensure that the track clearance green does not terminate before the gates block access to the crossing. This section does not need to be completed if the interconnect circuit includes a gate-down feature and the controller unit is properly programmed to hold the track clearance phase(s) in the green interval until the gate arm is detected to be in the horizontal position. All newly installed or modified preemption systems should include the gate-down circuit as part of the preemption system design. If the gates do not block access to the crossing before the expiration of the track clearance green, it is possible that vehicles can continue to cross the tracks and possibly stop on the tracks. However, the track clearance green interval has already expired and there will be no further opportunity to clear. This potentially hazardous condition is called the "preempt trap".

The Clearing of Clear Storage Distance section (Lines 56 to 61) focuses on efficiency by calculating duration of the track clearance green interval that is needed to clear the clear storage distance (CSD in Figure 1), or a specific portion thereof.

Preempt Trap Check (Use if Gate-Down Circuit is Not Present)

Line 47. Advance preemption time provided is the duration the preempt sequence is active in the highway traffic signal controller before the activation of the railroad active warning devices. Enter the APT

value to be used from either Line 35 or Line 46. If no APT is provided (simultaneous preemption), enter zero on Line 47. If using this section on a stand-alone basis to determine an appropriate track clearance green time for existing conditions, enter the existing APT currently provided by the railroad.

Line 48. Multiplier for maximum APT due to train deceleration is a value that relates the maximum duration of the advance preemption time (APT) to the minimum value designed by the railroad. Although the railroad designs for a minimum duration for the APT, it is probable that in most cases the actual duration of the APT will be longer than the guaranteed duration. This variability in APT occurs due to "train handling", which a term that describes the acceleration and deceleration of trains on their approach to the crossing. If a train accelerates or decelerates while approaching to the crossing, the railroad warning system cannot estimate the arrival time of the train at the crossing accurately, resulting in variation in the actual duration of APT provided. This variation needs to be taken into account to ensure safe operation.

To make sure that the preempt trap does not occur we need to determine the maximum value of the APT so that a sufficiently long track clearance green interval can be provided to ensure that the gates block access to the crossing before the track clearance green ends. The maximum APT can be estimated by multiplying the advance preemption time provided by the railroad (Line 47) with the multiplier for maximum APT due to train deceleration. This value is only significant if the value for APT on Line 47 is non-zero. If APT is zero, continue to Line 49.

In the case where APT is provided, the difference between the minimum and maximum values of APT is termed excess APT. Excess APT usually occurs when the train decelerates on the approach to the crossing, or where train handling affects the accuracy of the estimated time of train arrival at the crossing so that the preempt sequence is activated earlier than expected. The amount of excess APT is increased by the following conditions:

- Increased variation in train speeds, since more trains will be speeding up and slowing down;
- Lower train speeds, since a fixed deceleration rate has a greater effect on travel time at low speeds than at higher speeds; and
- Longer warning times, because more time is available for the train to decelerate on the approach to the crossing.

The multiplier for maximum APT can be determined from field measurements as the largest advance preemption time observed (or the 95th percentile, if enough observations are available) divided by the value on Line 47. If no field observations are available, the multiplier for maximum APT can be estimated as 1.60 if warning time variability is high or 1.25 if warning time variability is low. High warning time variability can typically be expected in the vicinity of switching yards, branch lines, or anywhere low-speed switching maneuvers takes place. According to Section 16.30.10 of the *AREMA Signal Manual*, the railroad can provide a "timer for constant time between APT and CWT." The effect of such a "not to exceed" timer is to eliminate excess APT, and if provided, the multiplier on Line 48 can be set to 1.0.

Line 49. Maximum APT is largest value of the advance preemption time that can typically be expected, which corresponds to the earliest possible time the preemption sequence in the traffic signal controller will be activated before the activation of the railroad grade crossing warning system (flashing lights and gates). It is the calculated by multiplying the APT provided by the railroad (Line 47) with the multiplier for maximum APT due to train deceleration (Line 48).

Line 50. Time from start of flashing lights until gate is horizontal is the sum of the duration of flashing lights before gate descent start (Line 40) and the full gate descent time (Line 41). These values can be obtained from the railroad or observed in the field for existing conditions.

Line 51. Gates down after start of preemption is the maximum duration from when the preempt is activated in the highway traffic signal controller until the gates reach a horizontal position. Calculate this

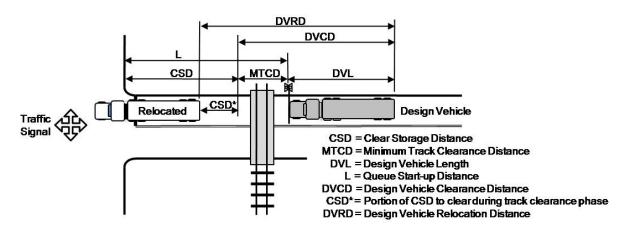
value by adding the maximum advance preemption time (Line 49) to the time from start of flashing lights until gate is horizontal (Line 50).

Line 52. Preempt verification and response time, from Line 3, is the number of seconds between the receipt at the traffic signal controller unit of a preempt call issued by the railroad's grade crossing warning equipment and the time the controller software actually begins to respond to the preempt call.

Line 53. Best-case conflicting vehicle or pedestrian time is the minimum time from when the preempt sequence is initiated in the traffic signal controller unit (i.e. after verification and response) until the track clearance green interval can start timing. In most cases, this value is zero, since the controller may already be in the track clearance phase(s) when the preempt starts timing, and therefore the track clearance green interval can start timing immediately. The best-case conflicting vehicle or pedestrian time may be greater than zero if the track clearance green interval contains phases that are not in normal operation (and conflicts with the normal phases), or where another phase or interval always has to terminate before the track clearance green interval can start timing.

Line 54. Minimum right-of-way transfer time is the minimum amount of time needed for the best case condition, prior to display of the track clearance green interval. Calculate the minimum right-of-way transfer time by adding the preempt verification and response time (Line 52) and the best-case conflicting vehicle or pedestrian time (Line 53).

Line 55. Minimum track clearance green time is calculated by subtracting the minimum right-of-way transfer time (Line 54) from gates down after start of preemption time (Line 51). This yields the minimum time that the track clearance green interval has to be active to avoid the preempt trap when a gate-down circuit is not present or not functional.



Clearing of Clear Storage Distance (Optional)

Figure 5 Relocation Distances During the Track Clearance Green Interval

Line 56. Time required for design vehicle to start moving, from Line 23, is the number of seconds that elapses between the start of the track clearance green interval and the time the design vehicle, which is located at the edge of the railroad crossing on the opposite side from the signalized intersection, begins to move.

Line 57. Design vehicle clearance distance (DVCD in Figure 5), from Line 24, is the length, in feet, which the design vehicle must travel in order to enter and completely pass through the railroad crossing's minimum track clearance distance (MTCD).

Line 58. Portion of CSD to clear during track clearance (CSD* in Figure 5) is the portion of the clear storage distance (CSD), in feet, that must be cleared of vehicles before the track clearance green interval

ends. For intersections with a CSD greater than approximately 150 feet, it is desirable—but not necessary—to clear the full CSD during the track clearance green interval. In other words, it is desirable to set Line 58 to the full value of CSD (Line 18). If the full CSD is not cleared, however, vehicles will be stopped in the CSD during the preempt dwell period, and if not serviced during the preempt dwell period, will be subject to unnecessary delays which may result in unsafe behavior. For CSD values less than 150 feet the full CSD is typically cleared to avoid the driver task of crossing the tracks followed immediately by the decision to stop or go when presented by a yellow signal as the track clearance green interval terminates.

Line 59. Design vehicle relocation distance (DVRD in Figure 5) is the distance, in feet, that the design vehicle must accelerate through during the track clearance green interval. It is the sum of the design vehicle clearance distance (Line 57) and the portion of CSD to clear during the track clearance green interval (Line 58).

Line 60. Time required for design vehicle to accelerate through DVRD is the amount of time required for the design vehicle to accelerate from a stop and travel the complete design vehicle relocation distance (DVRD). This time value, in seconds, can be found by locating your design vehicle relocation distance from Line 59 on the horizontal axis of Figure 2 and then drawing a line straight up until that line intersects the acceleration time performance curve for your design vehicle. For a semi-trailer, large school bus, or single unit vehicle, multiply the acceleration time with a correction factor obtained from Table 2 to estimate the effect of grade on the acceleration of the vehicle. For design vehicle relocation distances greater than 400 feet, use Equation 1 with the appropriate parameters listed in Table 3.

Line 61. Time to clear portion of clear storage distance is the total amount of time required (after the signal has turned green for the approach crossing the tracks) to begin moving a queue of vehicles through the queue start-up distance (L in Figure 5) and then move the design vehicle from a stopped position at the far side of the crossing completely through the portion of clear storage distance that must be cleared (CSD* in Figure 5). This value is the sum of the time required for design vehicle to start moving (Line 56) and the time for the design vehicle to accelerate through the design vehicle relocation distance, DVRD (Line 60).

Line 62. Track clearance green interval is the maximum value of the minimum track clearance green time to avoid preempt trap (Line 55), the time required to clear a portion of clear storage distance (Line 61), or the queue clearance time (Line 26).

REFERENCES

The following references were used in the development of the ODOT Guide For Determining Time Requirements For Traffic Signal Preemption At Highway-Rail Grade Crossings and these accompanying Instructions.

Ohio Department of Transportation. Ohio Manual on Uniform Traffic Control Devices (OMUTCD). 2005 Edition.

Institute of Transportation Engineers (ITE). *Determining Vehicle Signal Change and Clearance Intervals*. An Informational Report prepared by ITE Technical Council Task Force 4TF -1, August 1994.

American Association of State Highway & Transportation Officials (AASHTO). A Policy on Geometric Design of Highways and Streets. (Green Book). 2001.

Marshall, P.S. and W.D. Berg. *Design Guidelines for Railroad Preemption at Signalized Intersections*. In ITE Journal Volume 67, Number 2, February 1997, pp. 20-25.

American Railway Engineering and Maintenance-of-Way Association (AREMA). *Communications and Signals Manual of Recommended Practices*. 2009.

Engelbrecht, R.J., S. Sunkari, T. Urbanik, and K. Balke. *The Preempt Trap: How to Make Sure You do Not Have One*. Texas Department of Transportation Project Bulletin 1752-9, October, 2000. On the Internet at <u>http://tti.tamu.edu/product/catalog/reports/1752-9.pdf</u>. Link valid May 2003.